

Bayesian Networks & Causal Graphs

Presenter: Hannah Chen

2023/06/28



Overview

Bayesian Networks

Causal Axioms

Markov Equivalence

Statistical Modeling

$$P(x_1, x_2, \dots, x_n) = P(x_1) \prod_{i=2}^n P(x_i | x_1, \dots, x_{i-1}) \quad (\text{chain rule})$$

$$P(x_1, x_2, x_3, x_4) = P(x_1)P(x_2 | x_1)P(x_3 | x_1, x_2)P(x_4 | x_1, x_2, x_3)$$

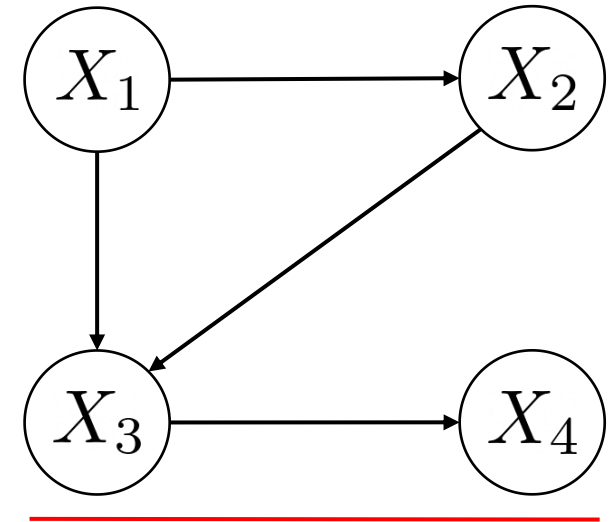
x_1	x_2	x_3	$P(x_4 x_3, x_2, x_1)$
0	0	0	α_1
0	0	1	α_2
0	1	0	α_3
0	1	1	α_4
1	0	0	α_5
1	0	1	α_6
1	1	0	α_7
1	1	1	α_8

} 2^{n-1} parameters!

Bayesian Networks

Local Markov assumption: Given its parents in DAG, a node X is independent of all of its non-descendants.

$$P(x_1, x_2, \dots, x_n) = \prod_i P(x_i \mid pa_i)$$



Bayesian $P(x_1, x_2, x_3, x_4) = P(x_1)P(x_2 \mid x_1)P(x_3 \mid x_1, x_2)P(x_4 \mid x_3)$

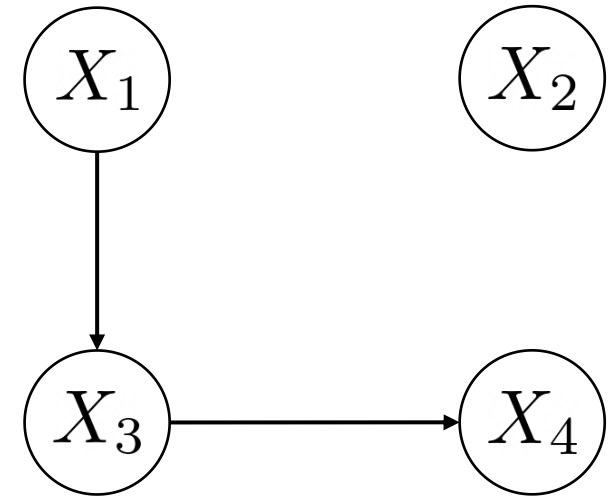
Statistical $P(x_1, x_2, x_3, x_4) = P(x_1)P(x_2 \mid x_1)P(x_3 \mid x_1, x_2)P(x_4 \mid x_1, x_2, x_3)$

Bayesian Networks

Local Markov assumption: Given its parents in DAG, a node X is independent of all of its non-descendants.

$$P(x_1, x_2, \dots, x_n) = \prod_i P(x_i | pa_i)$$

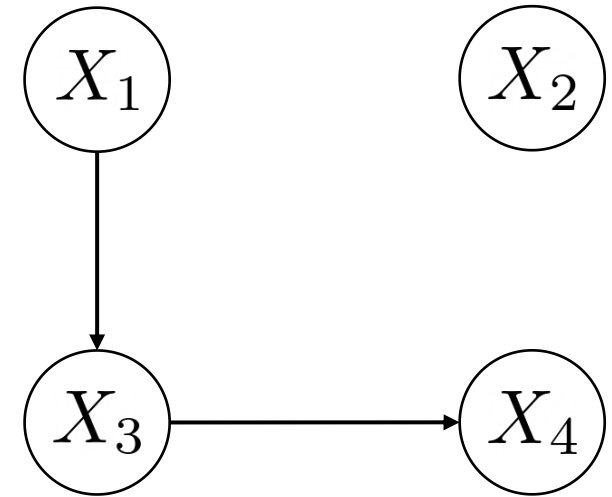
$$P(x_1, x_2, x_3, x_4) = ?$$



Bayesian Networks

Local Markov assumption: Given its parents in DAG, a node X is independent of all of its non-descendants.

$$P(x_1, x_2, \dots, x_n) = \prod_i P(x_i | pa_i)$$



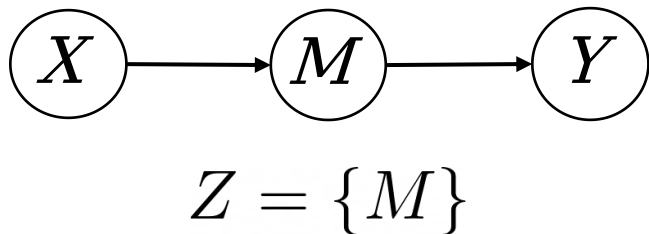
$$P(x_1, x_2, x_3, x_4) = P(x_1)P(x_2)P(x_3 | x_1)P(x_4 | x_3)$$

Global Markov Assumption

Given that P is Markov with respect to G (local Markov),

$$\underline{X \perp\!\!\!\perp_G Y \mid Z} \Rightarrow \underline{X \perp\!\!\!\perp_P Y \mid Z}$$

d-separation in graph G implies **conditional independence in distribution P**

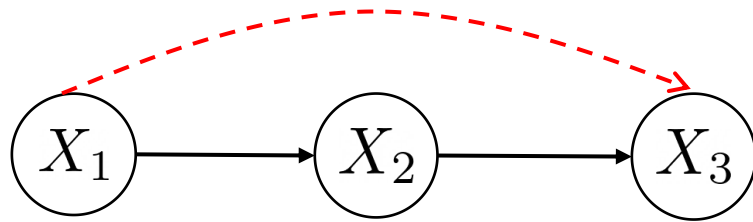


Local Markov \iff Global Markov

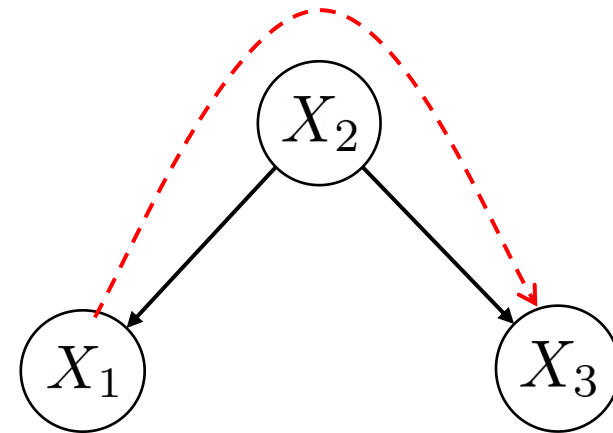
Markov assumption

Flow of Association: Chains and Forks

Association

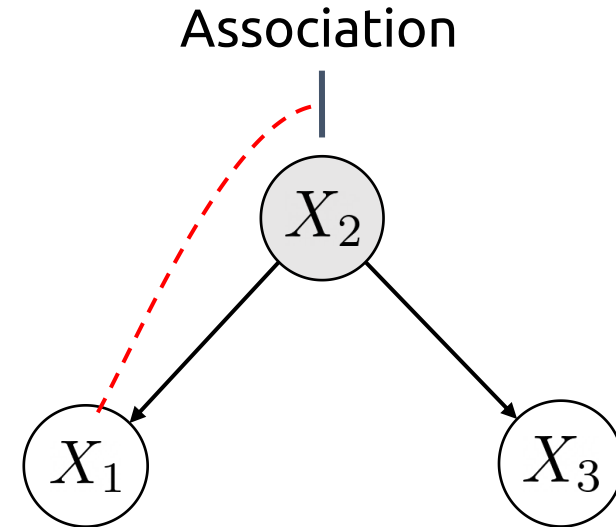
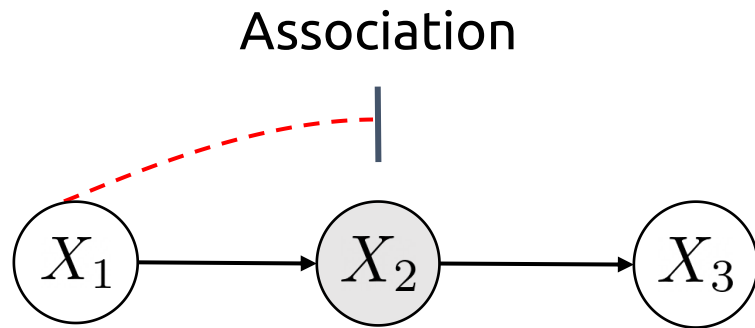


Association



$$X_1 \not\perp\!\!\!\perp X_3$$

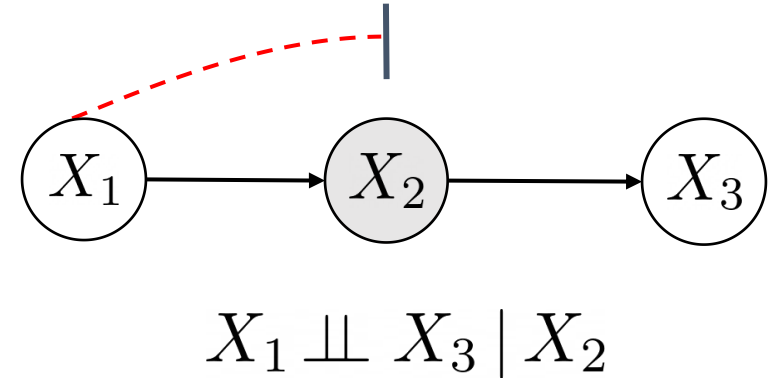
Flow of Association: Chains and Forks



$$X_1 \perp\!\!\!\perp X_3 \mid X_2$$

Proof: Conditional Independence in Chains

Show: $P(x_1, x_3 | x_2) = P(x_1 | x_2)P(x_3 | x_2)$
 $\equiv P(x_3 | x_1, x_2) = P(x_3 | x_2)$



1. Bayesian factorization $P(x_1, x_2, x_3) = P(x_1)P(x_2 | x_1)P(x_3 | x_2)$

2. Bayes' rule $P(x_1, x_3 | x_2) = \frac{P(x_1, x_2, x_3)}{P(x_2)} = \frac{P(x_1)P(x_2 | x_1)P(x_3 | x_2)}{P(x_2)}$

3. Bayes' rule again $P(x_1, x_3 | x_2) = \frac{P(x_1, x_2)}{P(x_2)}P(x_3 | x_2) = P(x_1 | x_2)P(x_3 | x_2)$

Flow of Association: Immoralities

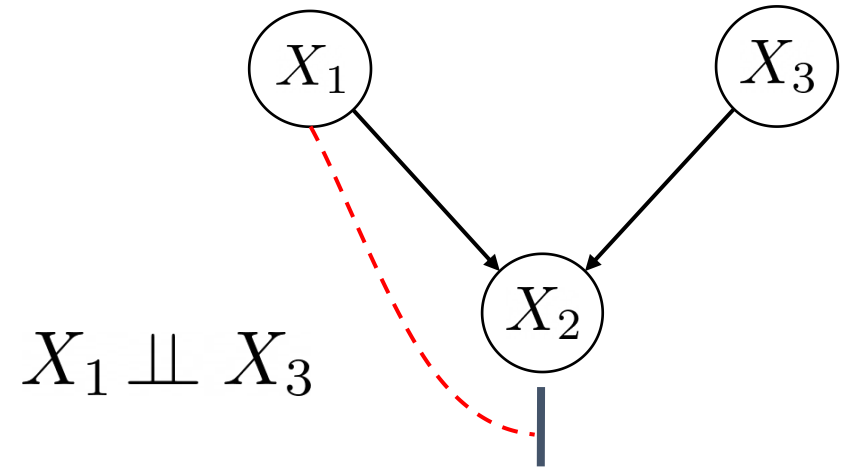
Show: $P(x_1, x_3) = P(x_1)P(x_3)$

$$P(x_1, x_3) = \sum_{x_2} P(x_1, x_2, x_3)$$

$$= \sum_{x_2} P(x_1)P(x_3)P(x_2 | x_1, x_3) \quad (\text{Bayesian factorization})$$

$$= P(x_1)P(x_3) \sum_{x_2} \overbrace{P(x_2 | x_1, x_3)}^1$$

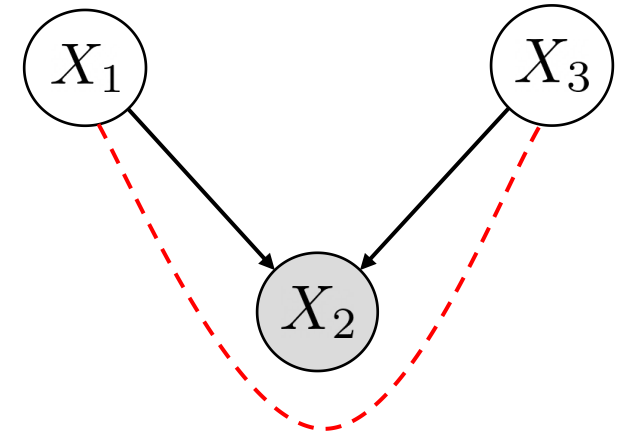
$$= P(x_1)P(x_3)$$



Flow of Association: Immoralities

Conditional dependence $X_1 \not\perp\!\!\!\perp X_3 \mid X_2$

$$P(x_1, x_3 \mid x_2) \propto P(x_2 \mid x_1, x_3)P(x_1)P(x_3) \\ \neq P(x_1 \mid x_2)P(x_3 \mid x_2)$$

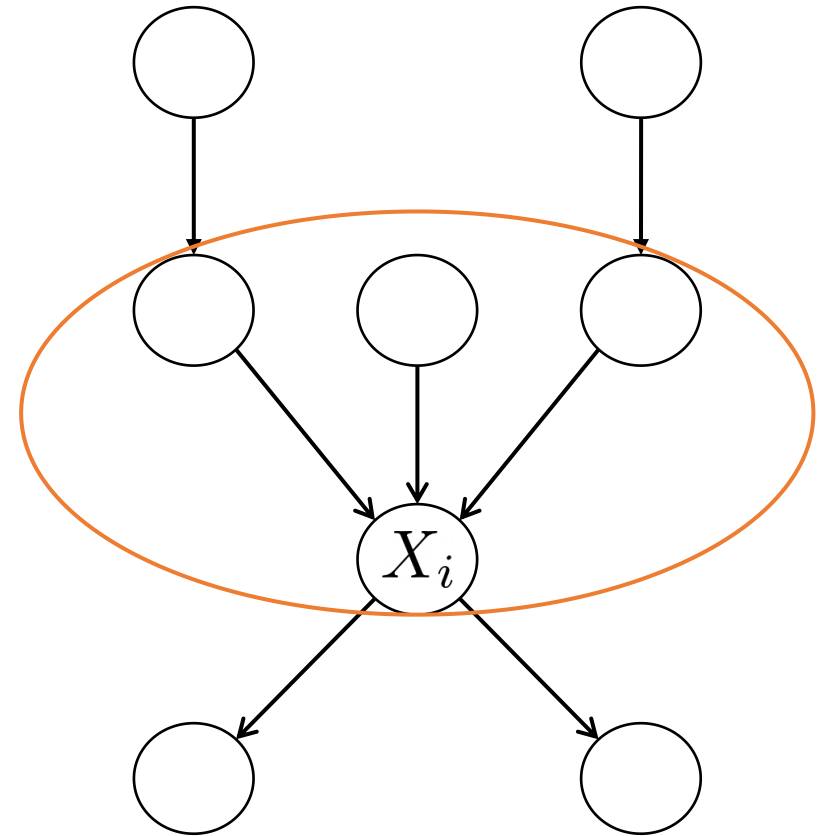


Intervention as Variables

Causal mechanism of X_i : $P(x_i | pa_i)$

Causal mechanism are modular
Interventions are local

$$do(X_i = x_i)$$



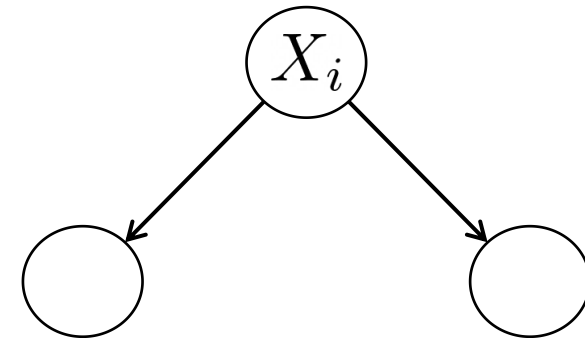
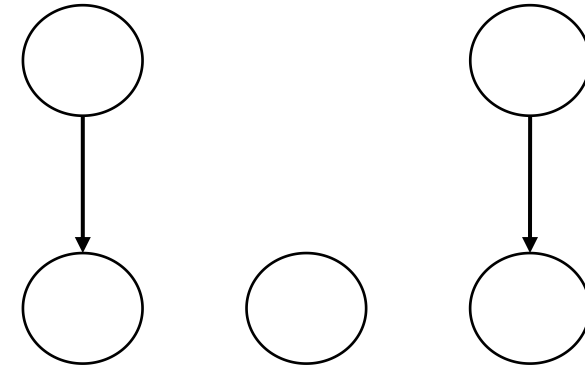
Intervention as Variables

Causal mechanism of X_i : $P(x_i | pa_i)$

Causal mechanism are modular

Interventions are local

$$do(X_i = x_i)$$



Modularity

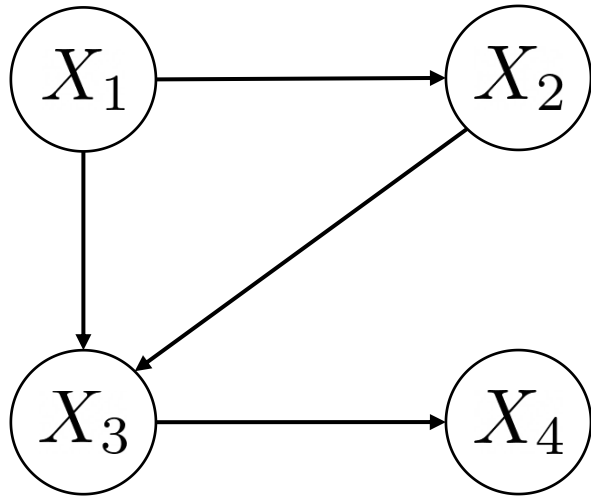
If we intervene on node X_i , then only $P(x_i|pa_i)$ changes. All other $P(x_j|pa_j)$ where $i \neq j$ remain unchanged.

More formally,

If we intervene on a set of nodes $S \subseteq [n]$, setting them to constants, then for all i , we have the following:

1. If $i \notin S$, then $P(x_i | pa_i)$ remains unchanged.
2. If $i \in S$, then $P(x_i | pa_i) = 1$ if x_i is the value that X_i was set to by the intervention; otherwise, $P(x_i | pa_i) = 0$. **consistent with the intervention**

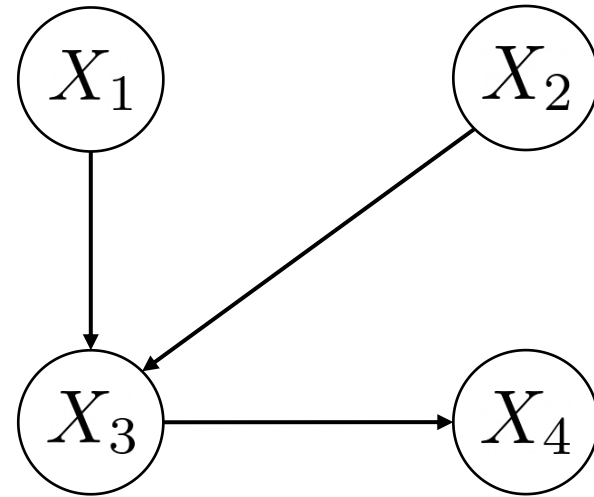
Modularity: Manipulated Graph



Observational distribution

$$P(x_1, x_2, x_3, x_4) \\ = P(x_1)P(x_2 | x_1)P(x_3 | x_1, x_2)P(x_4 | x_3)$$

$do(X_2 = x_2)$



Interventional distribution

$$P(x_1, x_2, x_3, x_4 | do(X_2 = x_2)) \\ = P(x_1) \cdot 1 \cdot P(x_3 | x_1, x_2)P(x_4 | x_3)$$

(Truncated factorization)

Interventions as Truncated Factorization

If x is consistent with the intervention (modularity):

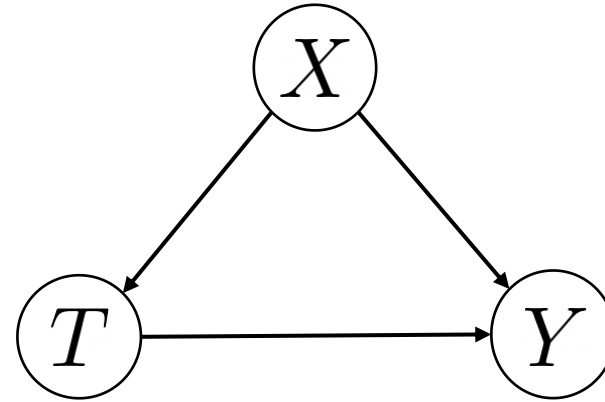
$$P(x_1, \dots, x_n \mid do(S = s)) = \prod_{i: x_i \notin S} P(x_i \mid pa_i)$$

Otherwise,

$$P(x_1, \dots, x_n \mid do(S = s)) = 0$$


Identification via Truncated Factorization

Identify $P(y | do(t))$



Bayesian factorization $P(y, t, x) = P(x)P(t | x)P(y | t, x)$

Truncated factorization $P(y, x | do(t)) = P(x)P(y | t, x)$

Marginalization $P(y | do(t)) = \sum_x P(y | t, x)P(x)$  Backdoor adjustment!

Causal Axioms

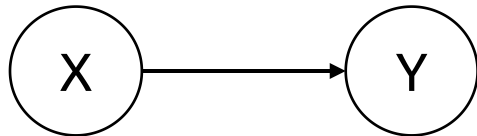
Connecting probabilities with causal graphs:

1. Markov Condition
2. Causal Minimality
3. Faithfulness Condition

Minimality Assumption

No subgraph of G also satisfies the Markov condition with respect to P

Markov assumption permits:



$$P(x, y) = P(x)P(y | x)$$



$$P(x, y) = P(x)P(y)$$

\Rightarrow Removing any edges from G , P would not be Markov with respect to G with the removed edges

Faithfulness Assumption

Markov Assumption: $X \perp\!\!\!\perp_G Y \mid Z \Rightarrow X \perp\!\!\!\perp_P Y \mid Z$

Causal graph \longrightarrow Data

Causal graph \longleftarrow Data

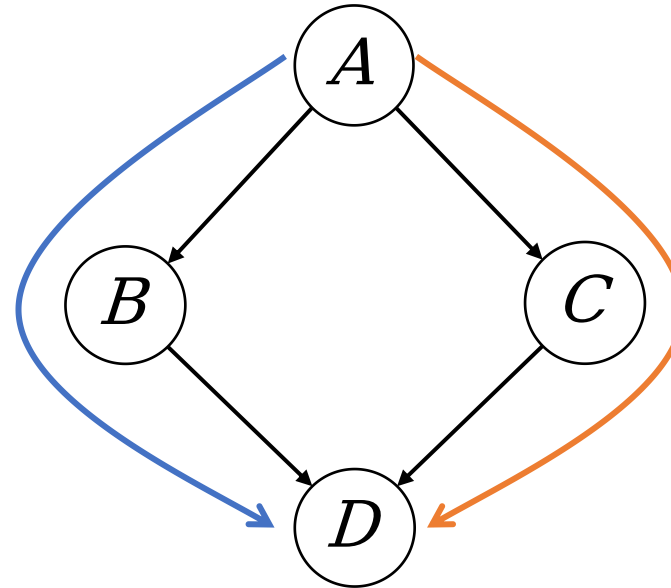
Faithfulness: $X \perp\!\!\!\perp_G Y \mid Z \Leftarrow X \perp\!\!\!\perp_P Y \mid Z$

Violation of Faithfulness

Faithfulness: $X \perp\!\!\!\perp_G Y \mid Z \Leftarrow X \perp\!\!\!\perp_P Y \mid Z$

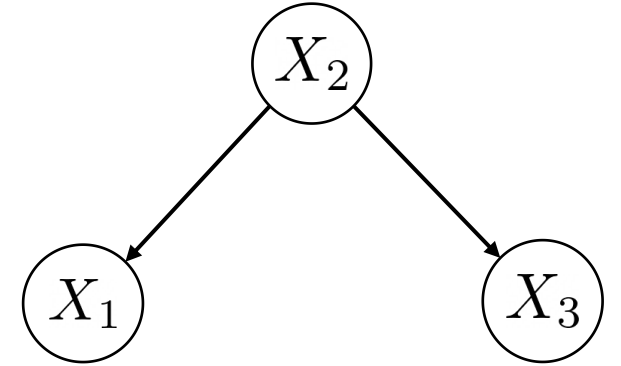
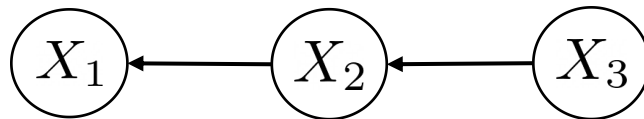
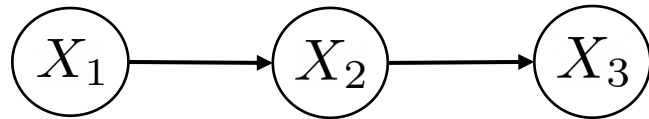
$$A \perp\!\!\!\perp D$$

but A and D are not d-separated



Two paths cancel
each other

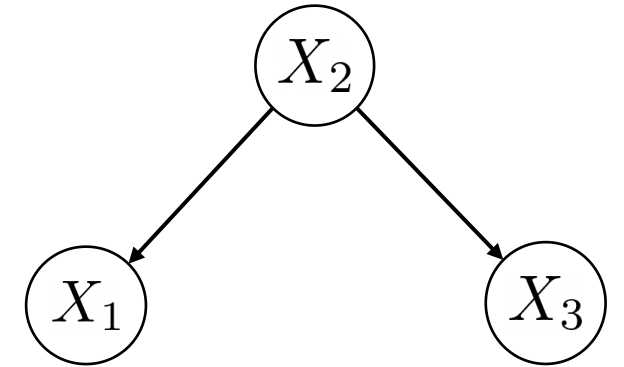
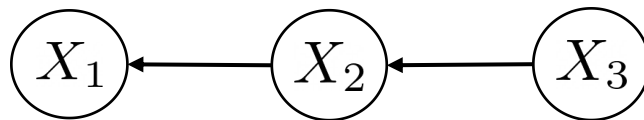
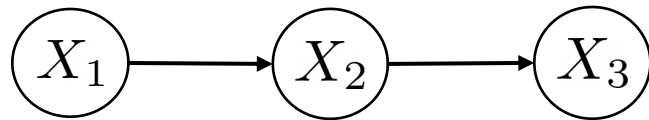
Markov Equivalence



They're all $P(x_1, x_2, x_3)$

But different Markov factorization

Markov Equivalence



Markov: $X_1 \perp\!\!\!\perp X_3 \mid X_2$

Minimality: $X_1 \not\perp\!\!\!\perp X_2$ & $X_2 \not\perp\!\!\!\perp X_3$

Faithfulness: $X_1 \not\perp\!\!\!\perp X_3$

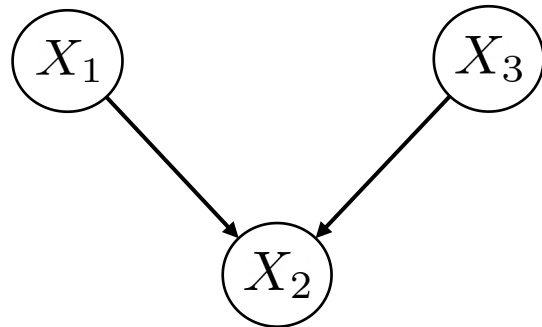
Markov equivalence class:

A set of DAGs that encode the same set of conditional independencies

Immoralities are Different

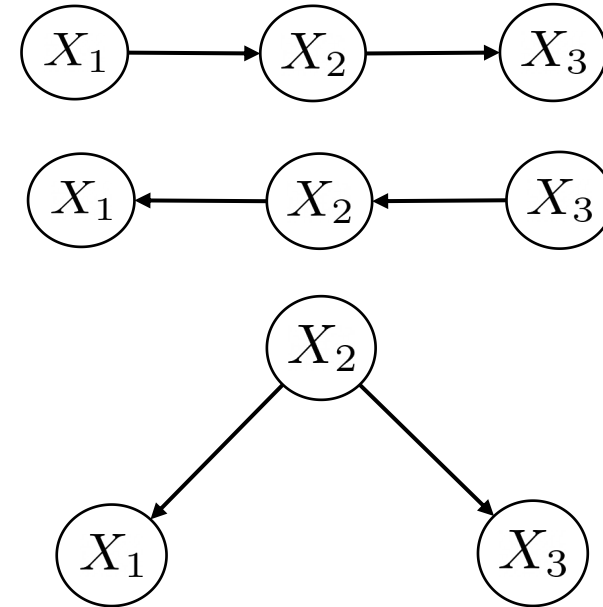
Markov equivalence class where

$$X_1 \perp\!\!\!\perp X_3 \text{ \& } X_1 \not\perp\!\!\!\perp X_3 \mid X_2$$



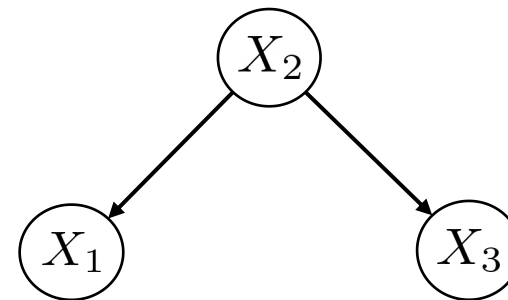
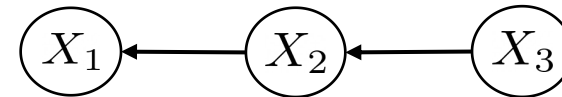
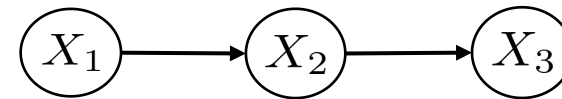
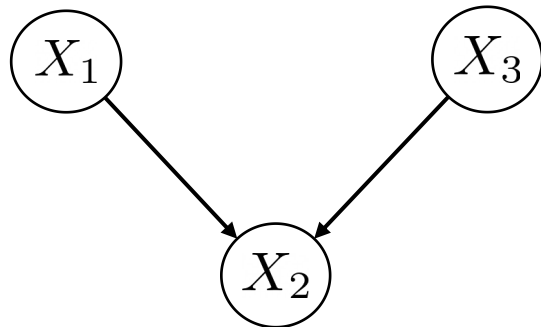
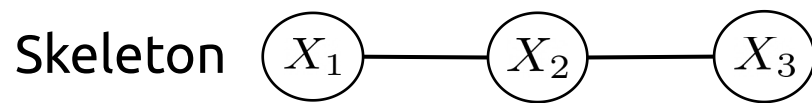
Markov equivalence class where

$$X_1 \perp\!\!\!\perp X_3 \mid X_2 \text{ \& } X_1 \not\perp\!\!\!\perp X_3$$



Markov Equivalence

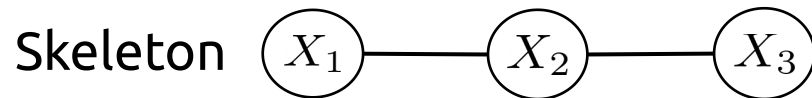
[Verma & Pearl, 1991] Two DAGs are Markov equivalent if and only if they have the same **skeleton** and the same **immoralities** (v-structures).



Markov Equivalence

Useful for causal discovery

[Verma & Pearl, 1991] Two DAGs are Markov equivalent if and only if they have the same **skeleton** and the same **immoralities** (v-structures).



Immorality

